



# Unmanned Aerial Systems in Agriculture

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**Seminar “Recent Developments of UAV Applications & Technology for  
Different Sectors & Problems and the Way Ahead”**

**Wednesday 20<sup>th</sup> of March 2013, kl. 9.00 – 16.00**

# Content

- UAS
- Agricultural applicability
- Precision farming
- Remote sensing in agriculture
- UAS benefits
- UAS applications in agriculture
- Some quantitative results
- UAV agri in Finland
- UAV as a working implement
- UAV regulations and agri
- UAS problems
- Future concepts
- Conclusions



# Unmanned Aerial System (UAS)

- Unmanned aerial vehicles (UAV)
- Remotely piloted vehicles (RPV)
- Remotely operated aircraft (ROA)
- Remotely controlled helicopters (RC-Helicopter)
- Low altitude remote sensing (LARS)
- Ground station





# Platforms



**Fig. 1** Examples of UAS currently used in environmental studies include **a** powered glider (Lelong et al. 2008), **b** powered parachute (Lelong et al. 2008), **c** helicopter (Eisenbeiss 2004), **d** fixed wing aircraft (Laliberte and Rango 2011), **e** Draganflyer X8 quadcopter, and **f** Aeryon Scout quadcopter

# Agricultural applicability

- A remote sensing tool for precision farming
  - Identify variations in the field (crops, diseases etc.)
  - Support variable rate application (VRA) technologies
  - Support farm strategic planning
  - Gives continuous (relative) information
- Working implement
  - Pesticide supply
  - Nutrient supply?
- Combination of these two
  - Future concepts



# Why precision farming?

- New tools for nitrogen management:
  - According to FAO, in the next 20 years, world food production must increase by 50%
  - Only about 50% of the N fertilizer added to cropping systems is taken up by the crop
  - The other 50% remains in soils or leaves cropping systems through air, surface water, or groundwater pathways
- Similar with other nutrients
- There is an increasing trend in the incidence of plant diseases. New tools are needed
- Pesticides are hazardous/unhealthy
- Farm economics/effectivity

- The basic underlying premise of remote sensing applications in precision farming is that differences in crop growth and soil condition can be detected through variations within the spectral responses
- Remote sensing and agriculture:
  - 1930's, precise measurements of cropland, USA
  - 1956 determine the prevalence of certain cereal crop diseases, USA
  - ...
    - soil properties monitoring and mapping
    - crop species classification
    - crop pest management
    - plant water stress detection
    - leaf chemical content analysis
    - weed control monitoring
    - yield mapping
    - plant nitrogen content
    - crop height
    - weed extent
    - leaf chlorophyll content
    - timely changes

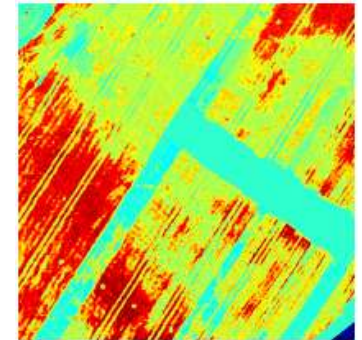
# Current/other remote sensing tools

The adoption of satellite imagery and aerial photos in PA has changed from 16.1 to 30.3 % between 2004 and 2009 in USA.

Typically used for crop growth, crop stress, and to predict crop yield

- **Aerial imaging**

- Clouds, high costs
- Operational complexity
- Lengthy delivery of products?



- **Satellite images**

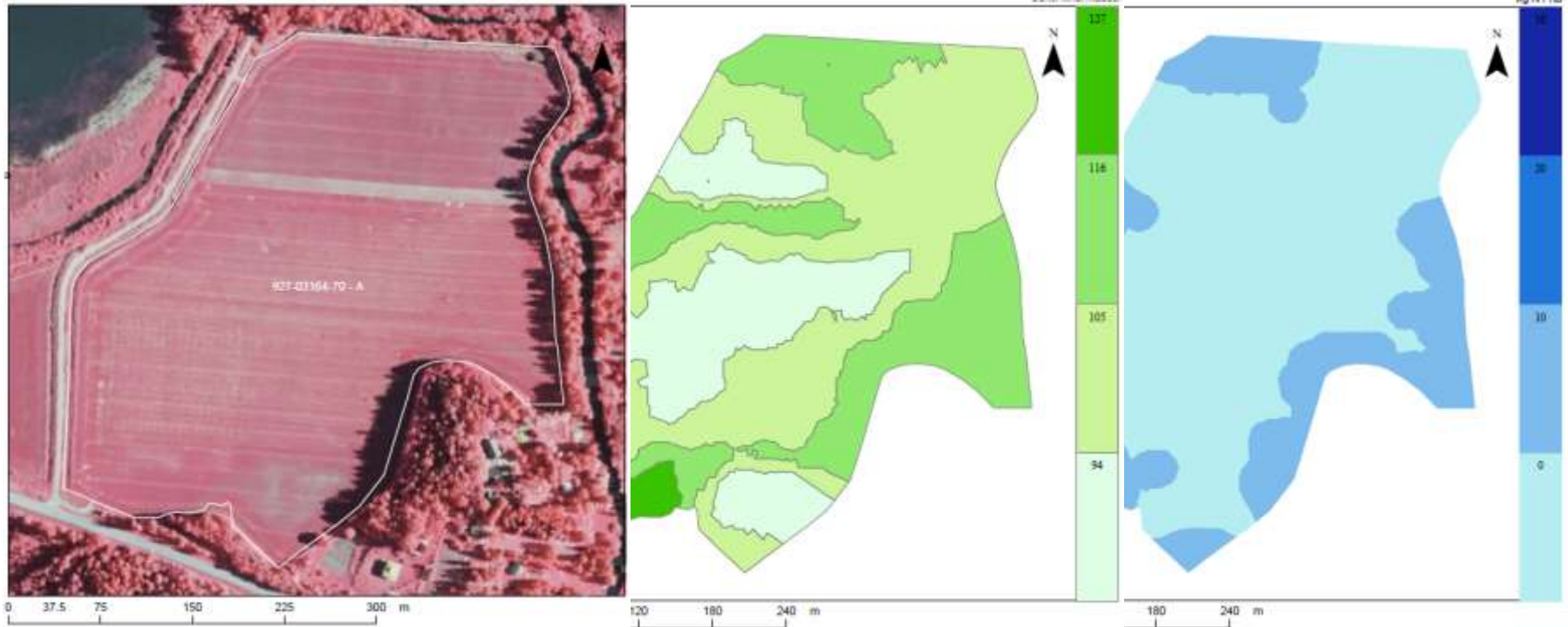
- Clouds
- Low resolution
- poor revisiting times

## Cameras on tractor

Has gained some market acceptance  
High invest  
Low resolution  
Limited adaptability



# Aerial images



Kemira Loris in Finland  
~1999-2004  
-3,5€-7,5€/ha  
-Max 250 users in Finland

Similar attempts e.g. in Netherlands

# Satellite images

- Medium resolution satellite imagery
  - e.g. LandsatTM, ASTER, SPOT5
  - Only for large scale studies
- Higher resolution satellite imagery
  - e.g. WorldView-2 and GeoEye-1
  - Frequency, clouds

GeoEye-2 Attributes & Capabilities	Imagery		Satellite		
		<i>Panchromatic</i>	<i>Multispectral</i>		
	<b>Spatial Resolution</b>	.34 meter	1.36 meters	<b>Swath Width</b>	14.5 km
	<b>Positional Accuracy</b>	5 meter CE90 (specification) 3-4 meter CE90 (expected)		<b>Off-Nadir Imaging</b>	Up to 60 degrees
	<b>Collection Capacity</b>	600,000 sq km/day (Pan + MSI)		<b>Dynamic Range</b>	11 bits per pixel
				<b>Mission Life</b>	Expected > 10 years
				<b>Revisit Time</b>	Approximately 3 days
				<b>Orbital Altitude</b>	681 km
				<b>Nodal Crossing</b>	10:30 am

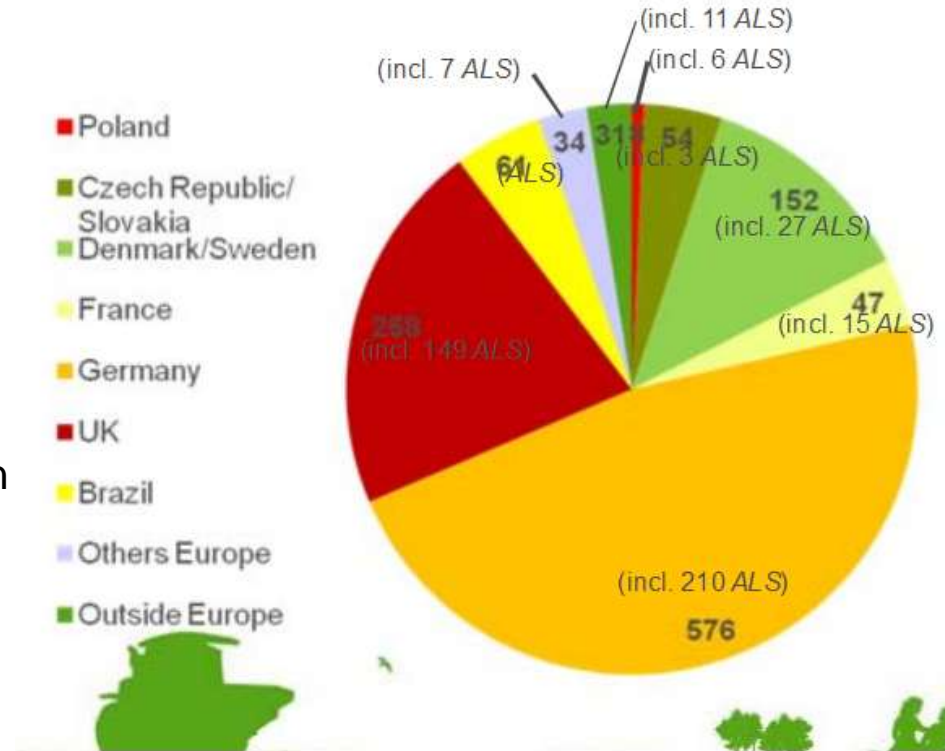
# On a tractor

- GreenSeeker
- Yara N-sensor
  - For nitrogen fertilization
  - ~15 000 €



# Yara-N-Sensor

- The yield increases **3.1% higher yield** (186 field trials)
- **Lodging** problems are reduced
- gives easier and safer **harvesting** and better grain **quality**
- Fertilizer costs can be lower
- **4.4 kg N/ha in higher nitrogen uptake** in the crop(82 field trials)
- Variable rate nitrogen fertilization reduces nutrient leaching
- **0.5 to 4 kg N/ha in reduced nitrogen leaching** depending on soil type



Source/more info:  
[http://www.njf.nu/filebank/files/20130201\\$090249\\$fil\\$QEBhVkgEHIAv7LxK7r58.pdf](http://www.njf.nu/filebank/files/20130201$090249$fil$QEBhVkgEHIAv7LxK7r58.pdf)

- Applications of remote sensing in general have been shown to be beneficial and profitable, but current applications in precision farming are still limited.
  - unavailability of reliable economic estimates of return from the application of remotely sensed images.
- the costs, availability, flexibility, and the processing of remotely sensed imagery from satellites have made their applications prohibitive and thus non-practical?



# UAS benefits



- Low cost of operation(?)
- High spatial resolution(?)
- High temporal accuracy(?)
- Flexibility in image acquisition programming(?)

# UAS applications in agriculture worldwide:

- small weed patches in rangelands 2005->
- monitoring crop biomass 2005->
- water stress in crops 2009
- mapping vineyard vigour 2012->
- examining the results of various nitrogen treatments on crops 2005->
- assess irrigation systems at the field scale
- sample pollen and spore (siitepöly, itiöt) 2005->
- agricultural disease agents 2008->
- Crop elevation 2011->

# Used sensors for image capture

## Optical & passive

- cameras
- cameras with a near infrared band
- multi-spectral camera
- hyper-spectral camera
- thermal image sensors

# Vineyard vigour

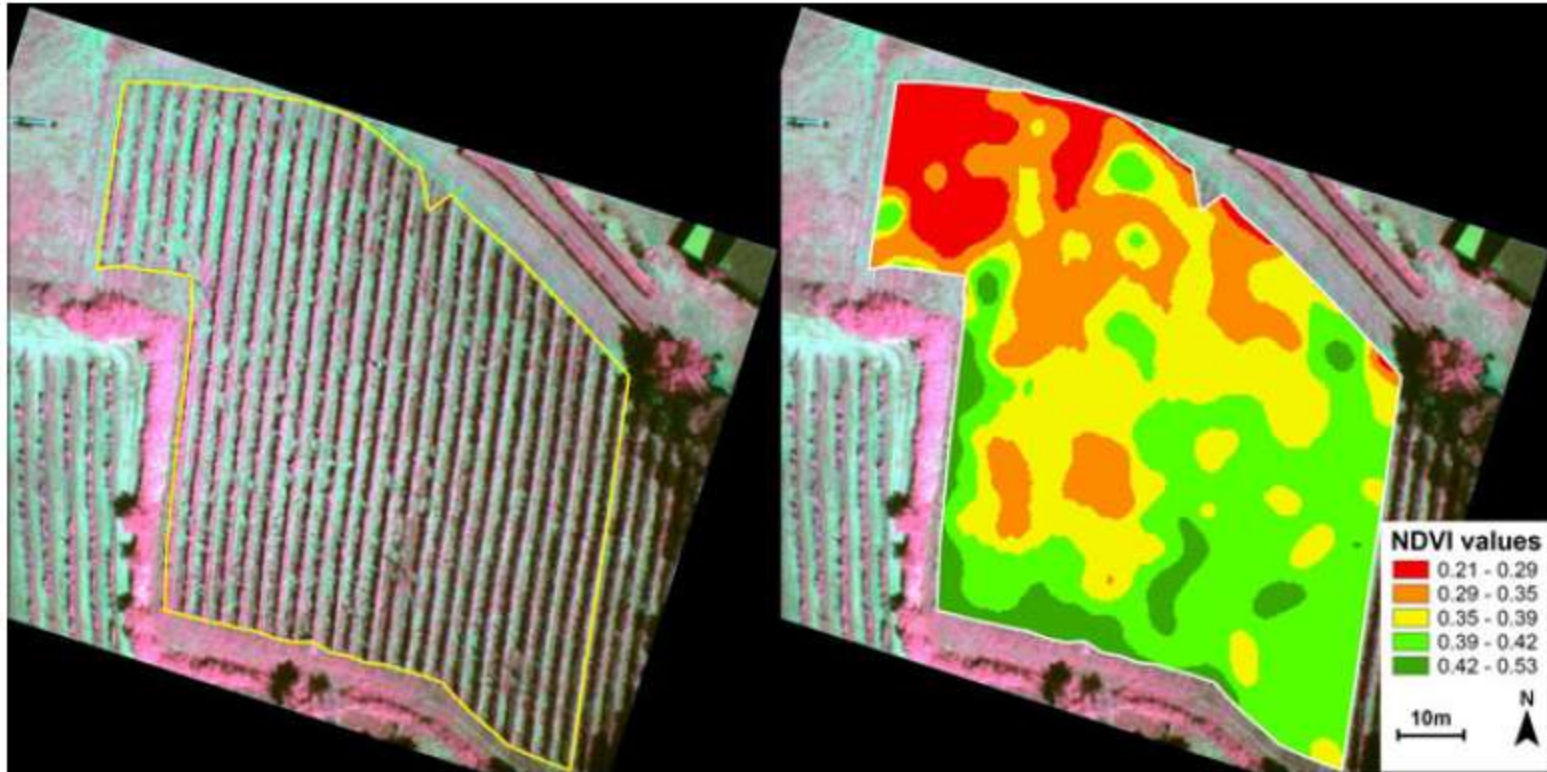


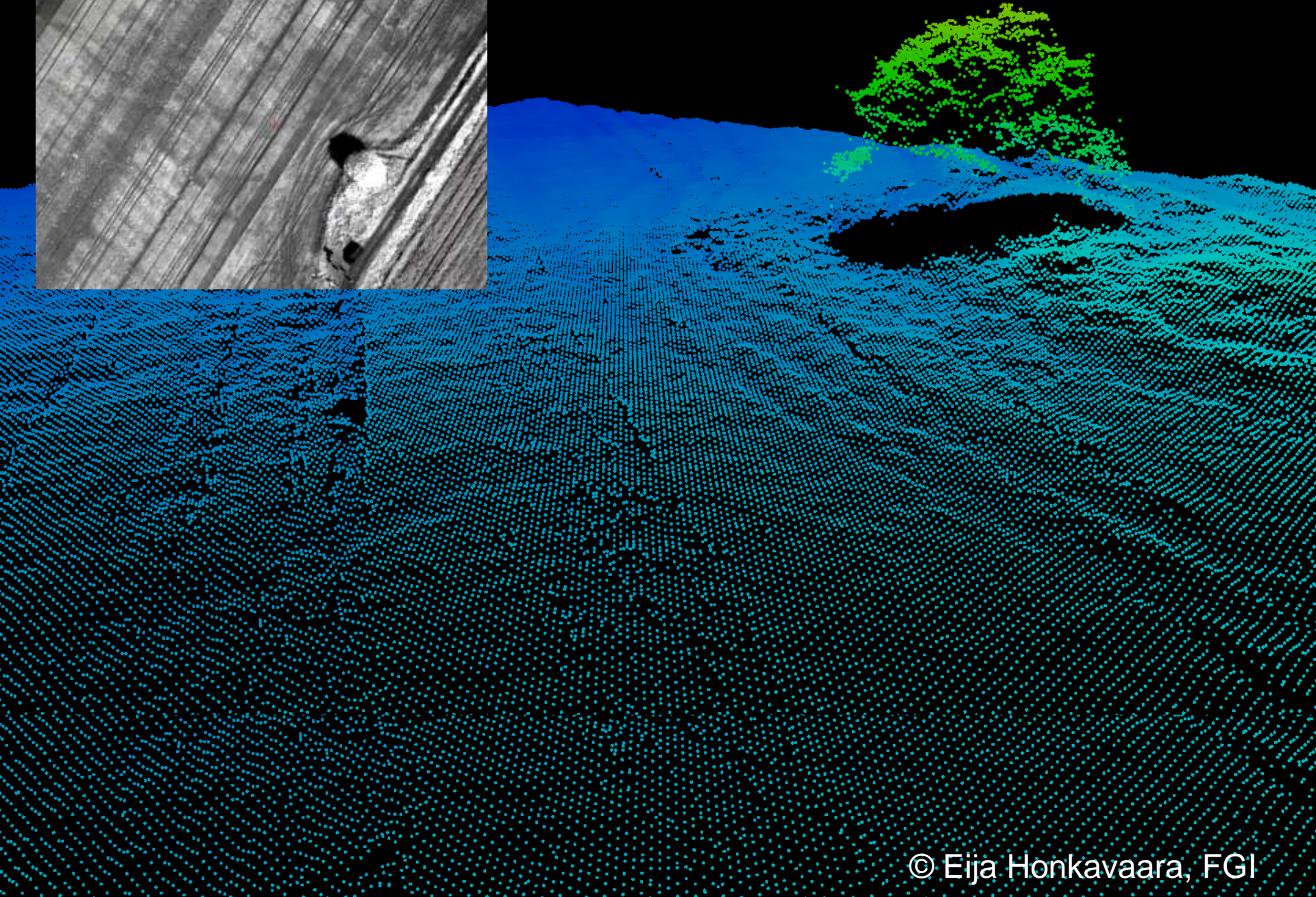
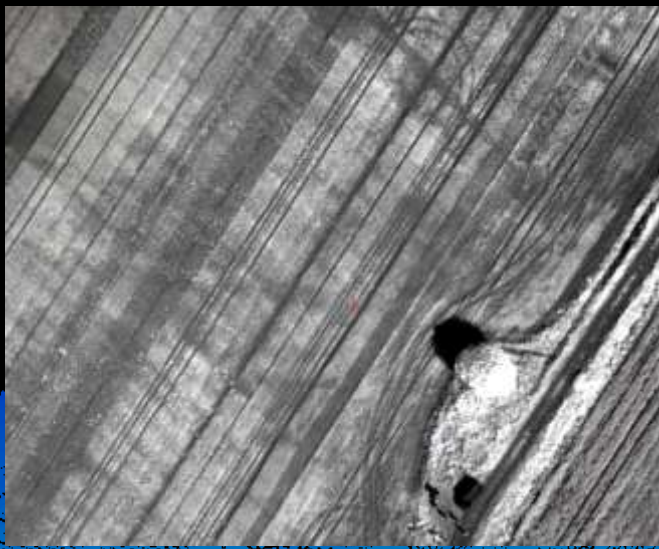
Fig. 2 Multi-spectral images of the Monteboro vineyard (*left*) false color image at 5 cm of spatial resolution and (*right*) classified NDVI based vineyard vigour map

# Irrigation systems





# Crop elevation



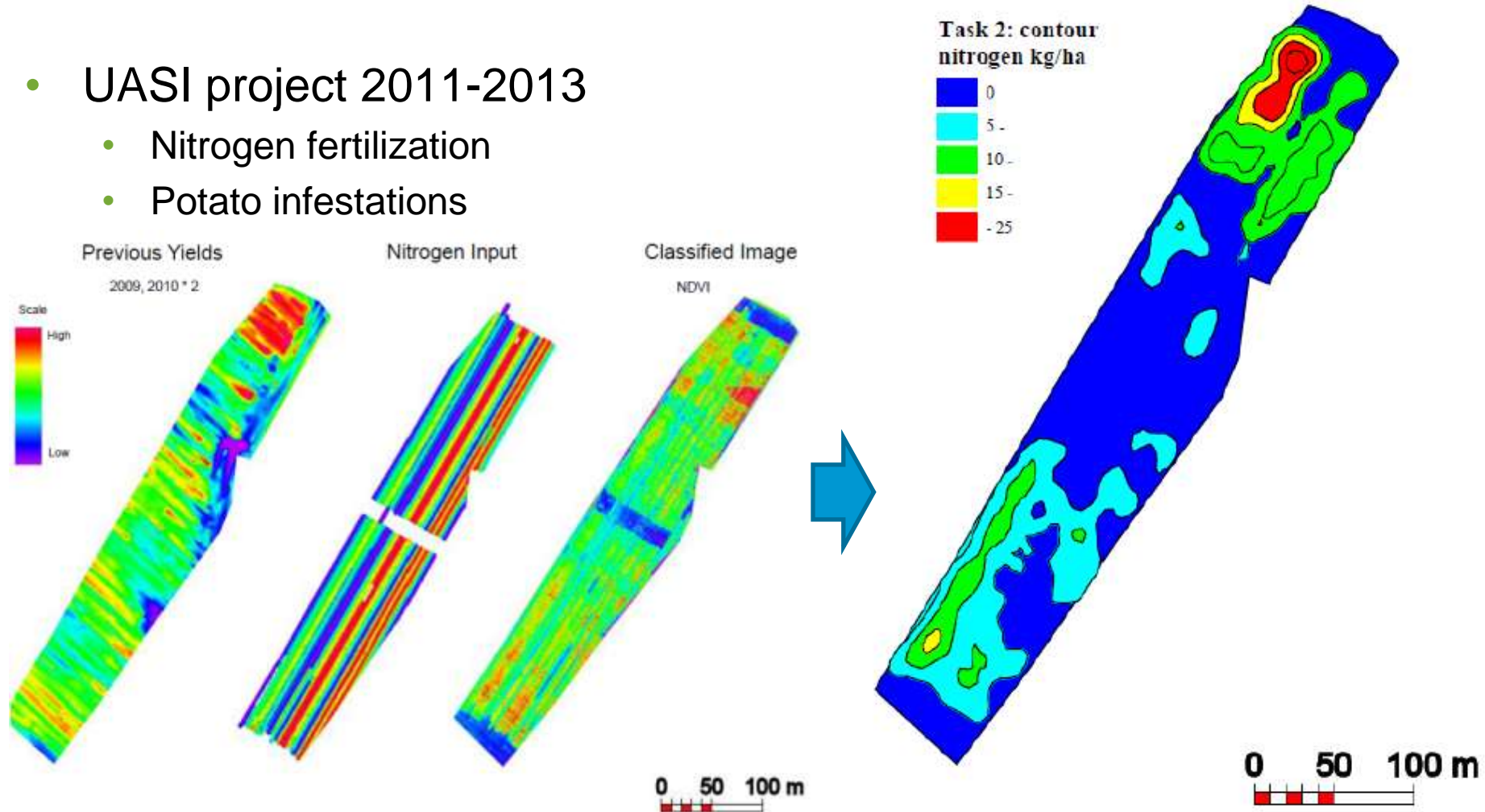
# Some quantitative results

- **Acquisition of NIR-green-blue digital photographs from unmanned aircraft for crop monitoring, 2010 USA**
  - Winter wheat,
  - LAI-2000 Plant Canopy Analyzer & GNDVI,  $R^2 = 0,79$
- **Remote sensing of vegetation from UAV platforms using lightweight multispectral and thermal imaging sensors, 2010 Germany**
  - Canopy temperature, water potential  $R^2=0,82$

**Typical publicized  $R^2$  results around 0,6-0,9**

# UAV and agriculture in Finland

- UASI project 2011-2013
  - Nitrogen fertilization
  - Potato infestations





# Some UASI platforms



# UAV as a working implement

- Mainly for spraying applications, since ~2007
- AG210, AG120
  - <http://www.youtube.com/watch?v=PtwshJkdeTQ>
  - <http://www.youtube.com/watch?v=Pa0xTDgcMV4>
  - <http://www.youtube.com/watch?v=rwE2lubaPOU>





# UAV regulations and agriculture

## **Spraying:**

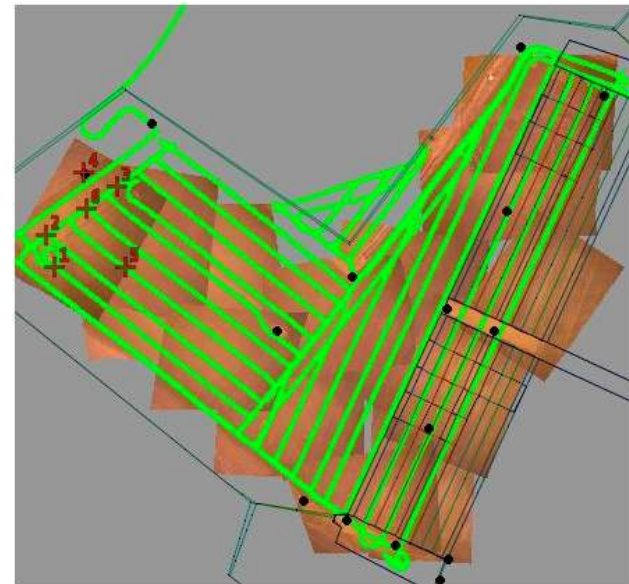
- Aerial spraying directives quite heavy
- Handheld spraying directives?

## **Aviation regulations:**

- The operator should always see the flying UAV
  - Remote farm and large area
- Cargo dumping in faulty situations
  - High concentration
- Residential area limitations
- Local regulations:
  - operator licences, insurances, UAV team

# UAS problems

- Platform reliability
- Platform stability
- Sensor capability
- Short flying time
- Payload limitations
- Platform prize
  
- Image quality
- Prosessing time
- Flying costs
- Relevance of the final product
- Disappearing accuracy



# However...

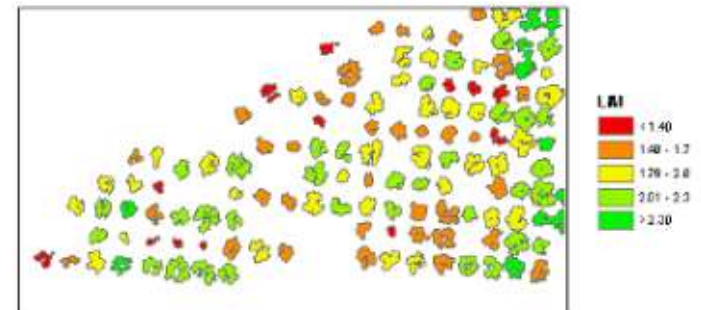
- Those problems are technological and could be solved with new technology development

## Current successful applications

- monitoring rangeland conditions
- monitoring vineyard conditions



a)



# Future concepts

## Better platforms

## New sensors onboard

- Active

## Better applications

- High value crops
- From relative zonal mapping to more accurate applications
- Farm machinery improvements

## Real time data analysis

- Disease spots etc. (no intact map needed)



# Future concepts

## **As an agricultural machine, e.g.:**

- Seeks the areas that needs to be threaten
- Threats the area
- Automatically changes battery and fills the tank
- Continues working



## Animation

<http://www.youtube.com/watch?v=4z3HNt5-ygQ>



# Conclusions

- Applications for localizing weeds and deceases, detecting vegetation differences and the production of an accurate elevation models are currently possible
  - Verifying benefits is difficult
- Many sensitive and separate parts, fragile chain
- Cumulative errors, important quality management
- Components for next generation models are available





**Remind the safety!**





# Thank you!

Precision Agric (2012) 13:693–712  
DOI 10.1007/s11119-012-9274-5

## The application of small unmanned aerial systems for precision agriculture: a review

Chunhua Zhang • John M. Kovacs

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